



# Robotic Crowd Biology with Maholo LabDroids

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Chief Scientific Officer (CSO)

# Humanoid

A type of robot replicates or imitates human's skilled movement and maneuvers using same tools and equipment.



*What the HUMANOID is NOT is ...  
a dedicated automation machine.*

A white industrial robotic arm is suspended in a laboratory or factory setting. The arm is positioned horizontally, with its joints and mechanical components visible. The background shows various pieces of equipment, including a metal table, a control panel, and other machinery. The lighting is bright and even.

# Hub Drivory

Researcher demand for versatility  
and expandability

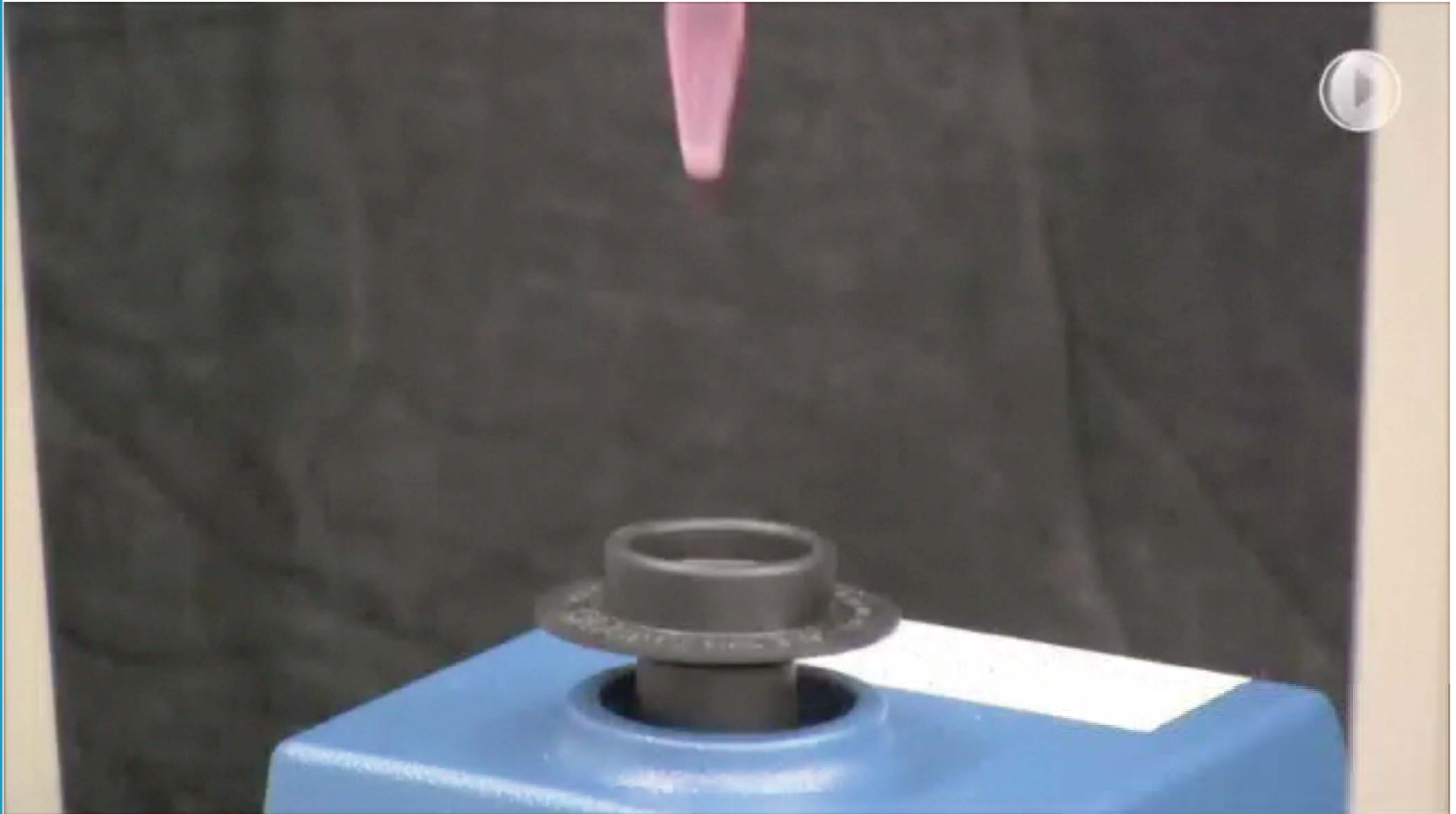
# Spin column manipulation



# TCA protein precipitation



# Vortex mixer

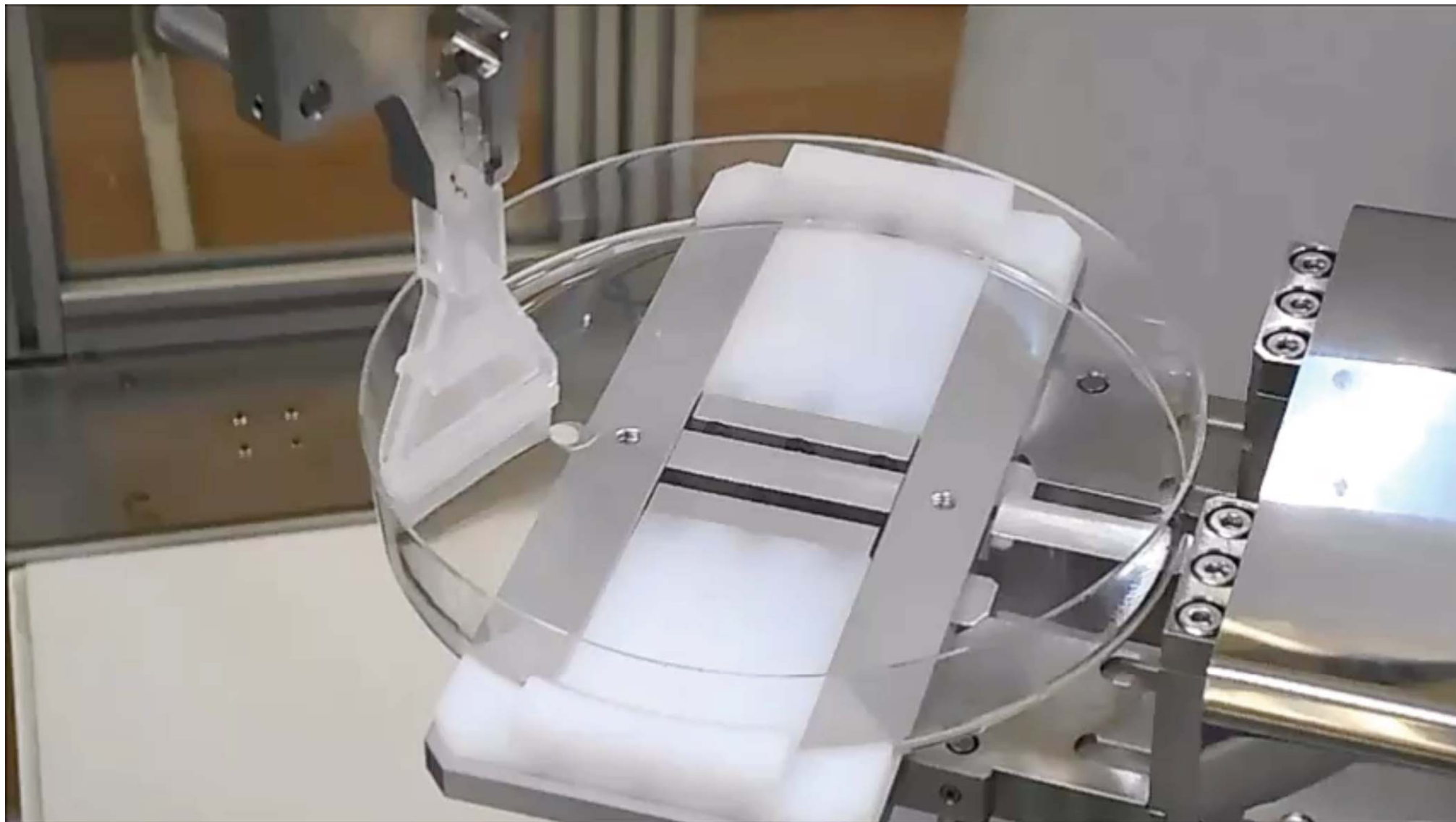


# Cell Scraping



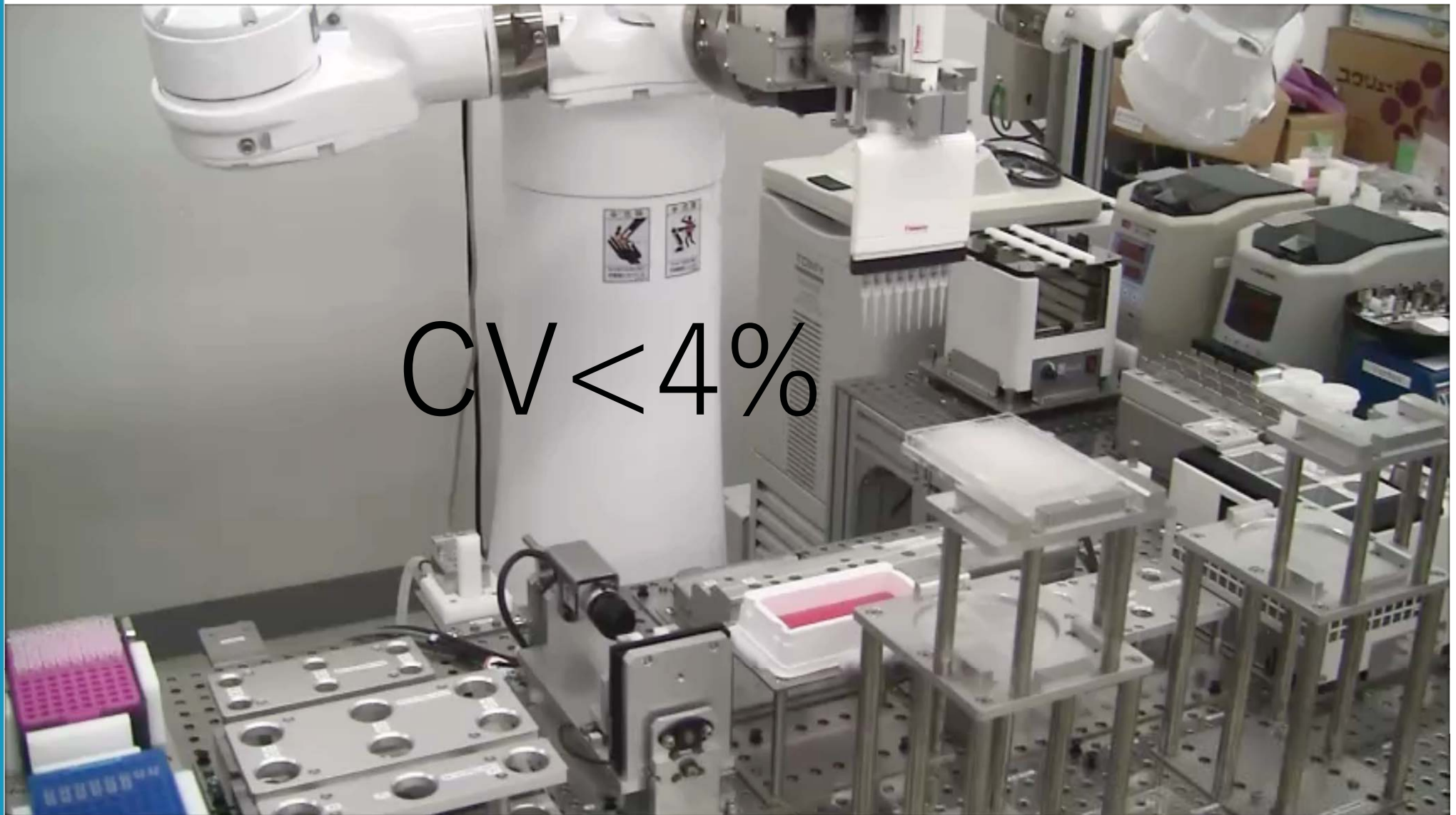
Jig free system



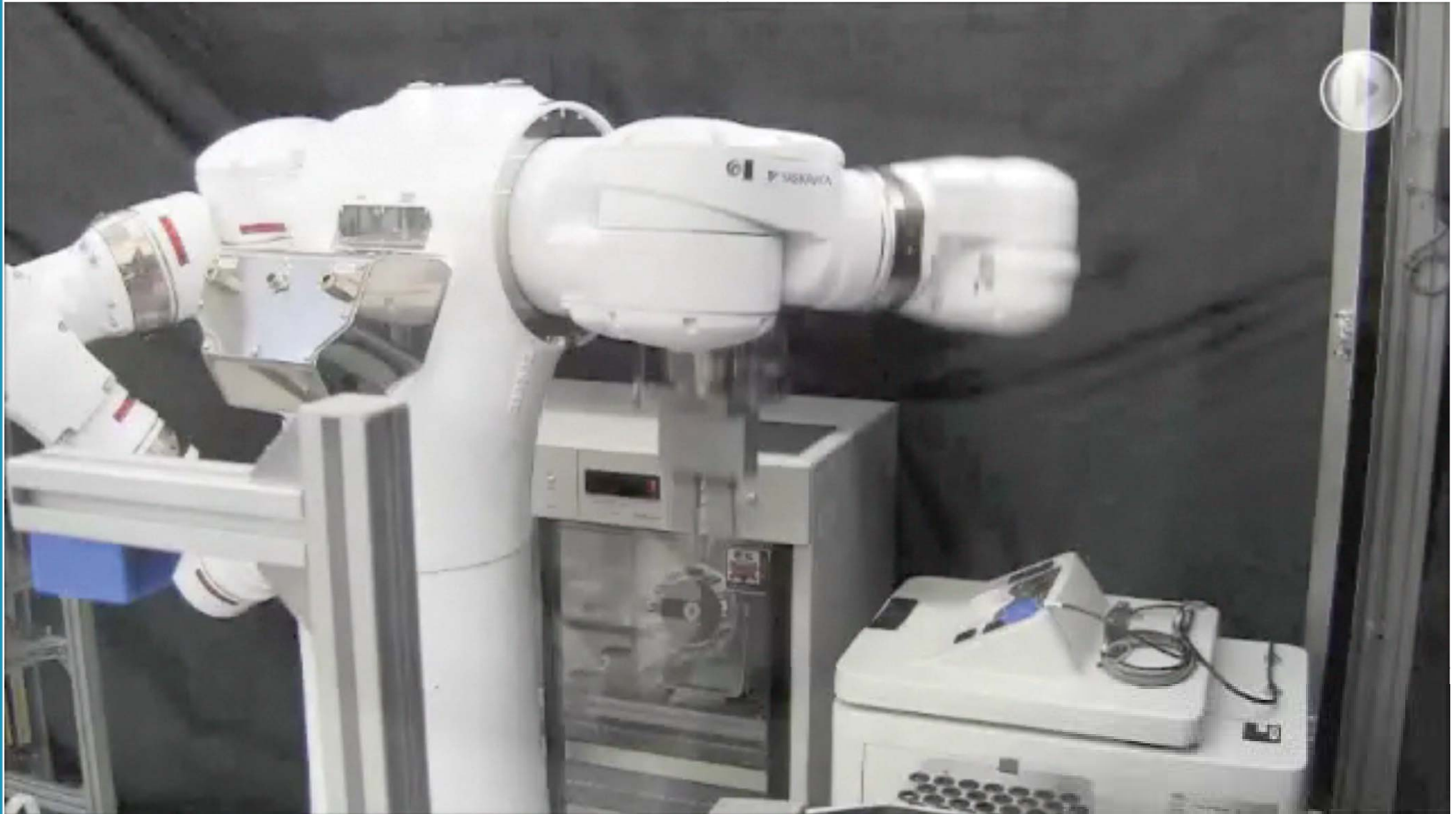




# 384 multiwell dispensing

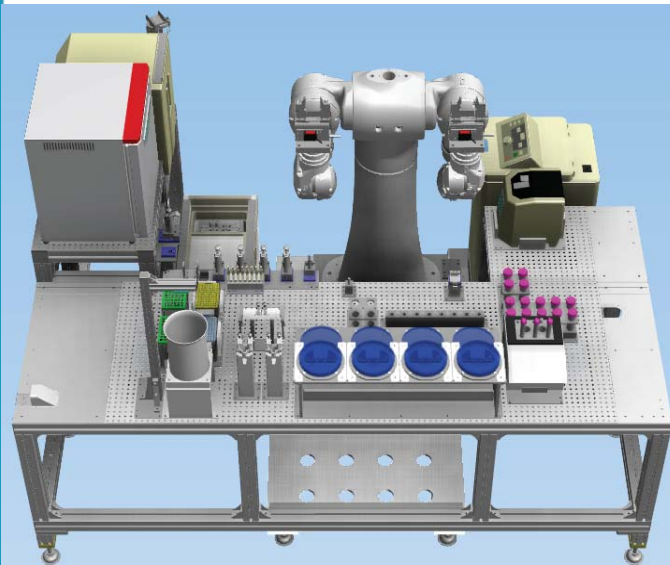


# Fridge and Rotator

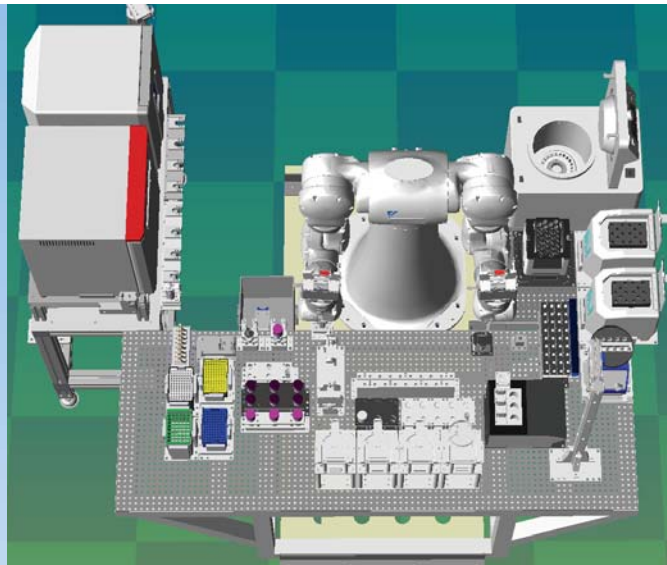


# Versatility of LabDroid

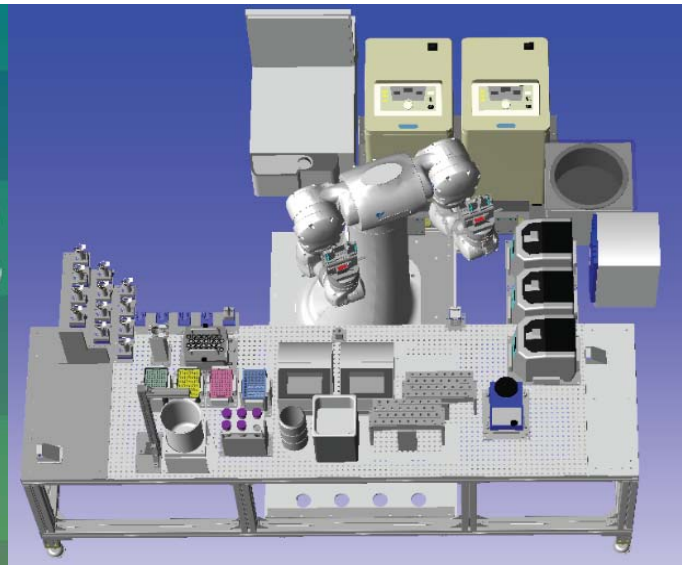
For Cell culture  
Cell-based screening



For Proteomics  
Metabolomics



For Genomics



# Beyond mere laboratory automation

LabDroid's main value: Optimization and standardization of protocols

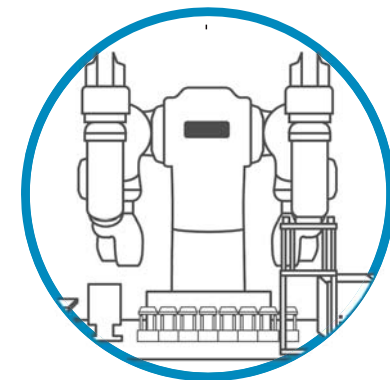
Improve efficiency  
and cut costs



Transfer human skills and  
expertise/maneuverability  
to LabDroid

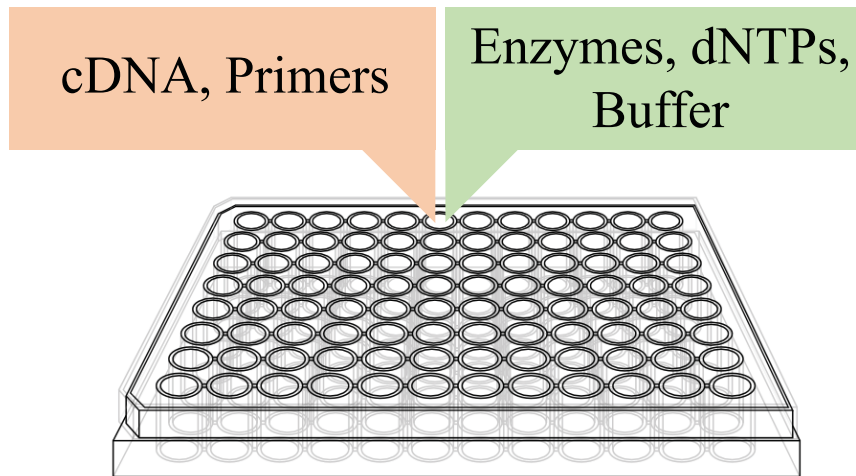
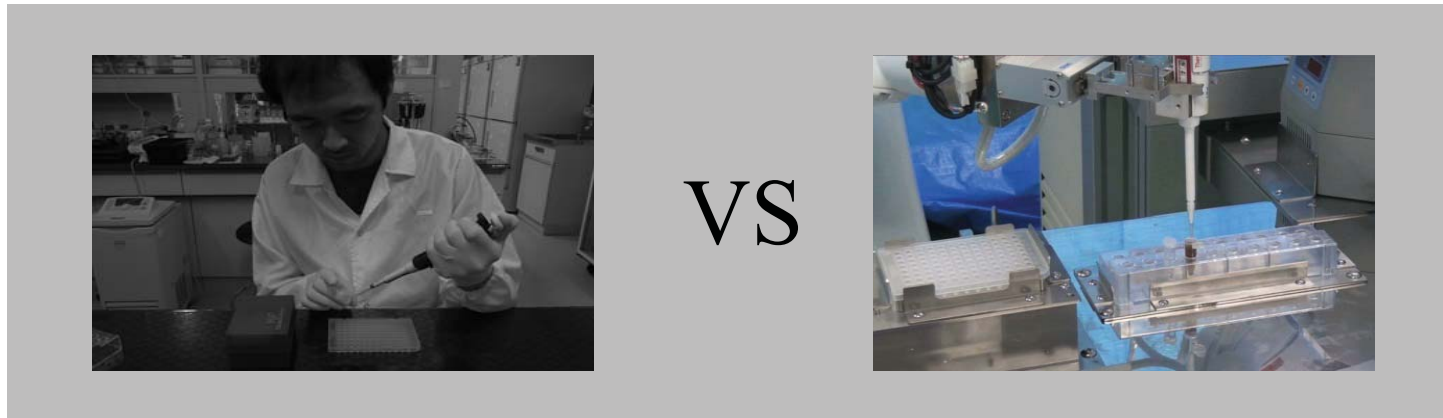


Visualize and digitize  
human skills and  
expertise/tacit knowledge



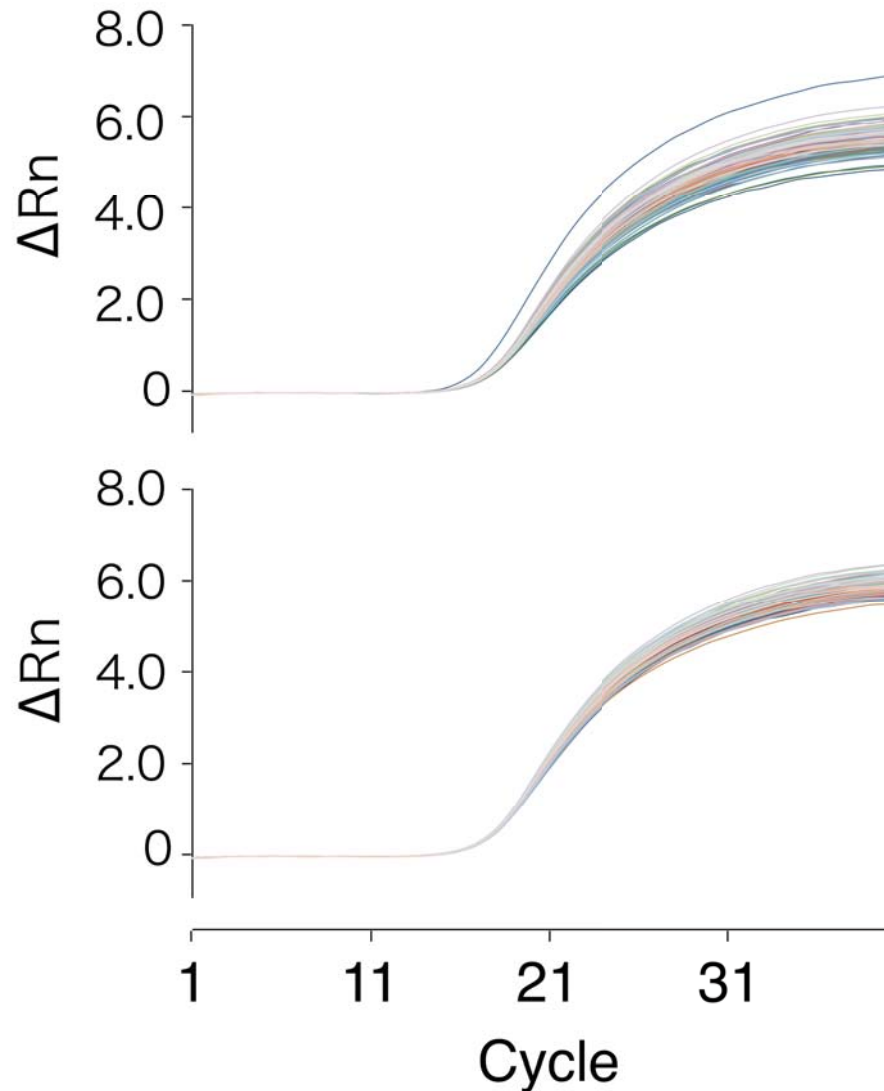
# Ex. 1 | Reproducibility in real-time PCR

Microvolume dispensing – accuracy crucial for quality results



# LabDroid outperforms skillful humans

## Real-time PCR profile



Manual

$CV \sim 10-20\%$

LabDroid

$CV < 4\%$

Record-breaking performance



# LabDroid outperforms skilled humans

Real-time PCR competition: humans *vs* LabDroid

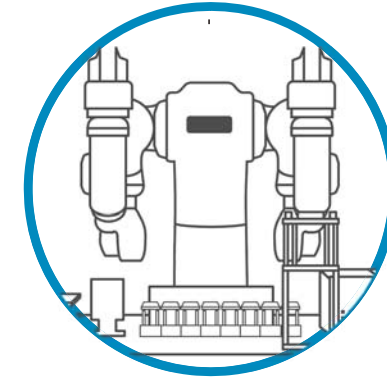
Best performer

$CV = 10\%$

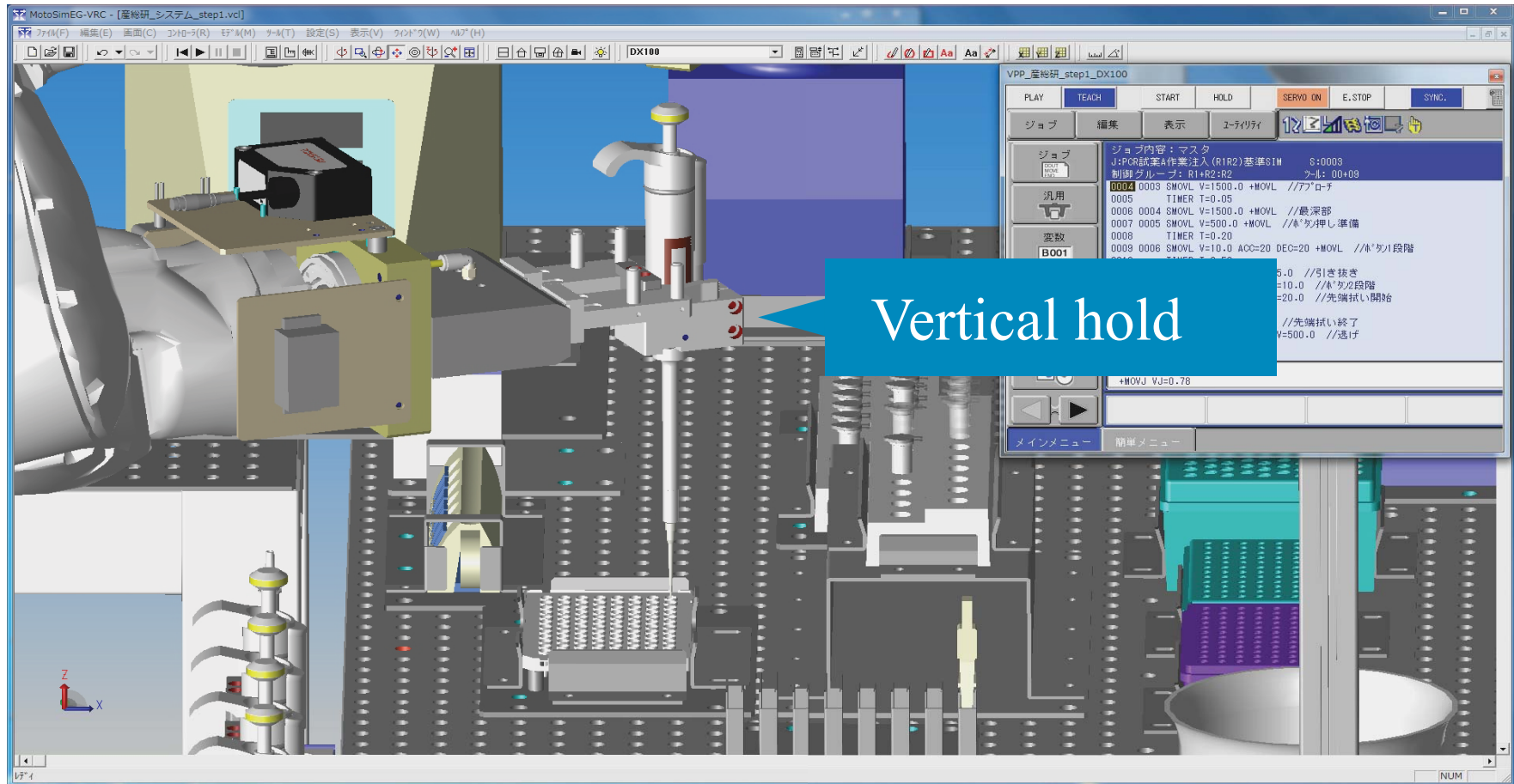


LabDroid

$CV < 4\%$



# Optimize performance of $\mu\text{L}$ scale pipetting

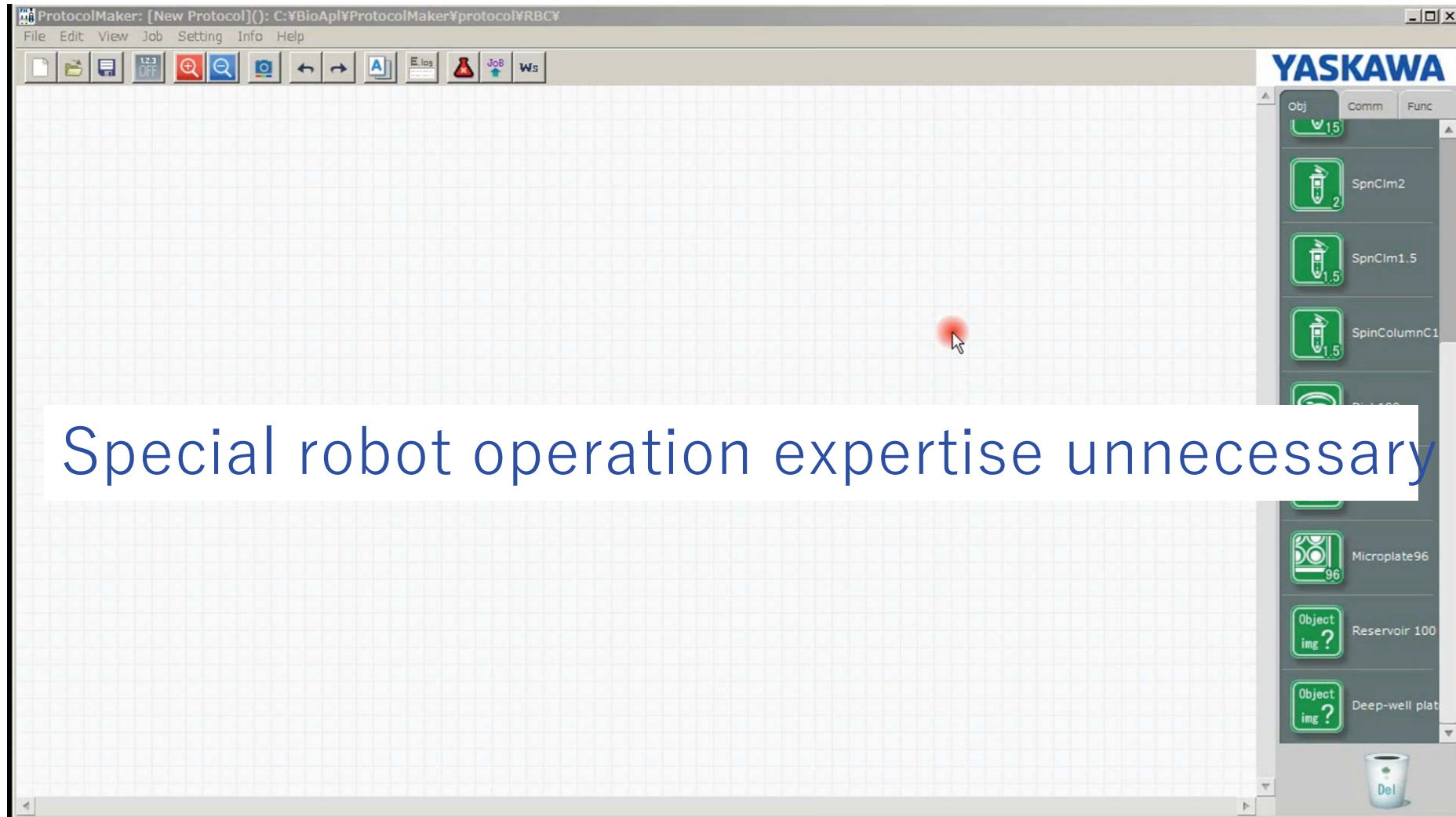


- Step 1 | Tip down 2 mm above well bottom
- 2 | First plunger push at 15 mm/sec
- 3 | Move tip up 2 mm, 0.5 mm/sec
- 4 | Wait 0.5 sec
- 5 | Second plunger push 30 mm/sec
- 6 | Raise
- 7 | Move up vertical



# Optimization interface: Protocol Maker

LabDroid is operated from a PC or tablet, equipped with software that allows researchers to set up any protocol simply and intuitively.



# Beyond mere laboratory automation

LabDroid's main value: Optimization and standardization of protocols

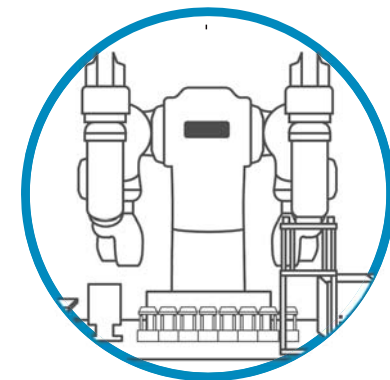
Outperforms humans



Transfer human skills and expertise/maneuverability to LabDroid



Visualize and digitize human skills and expertise/tacit knowledge



## Ex. 3 | Cell-based high-content screening

Failed to narrow down chemical library to discover hit chemicals by humans. Two researchers struggled for 2 years.

LabDroid achieved successful results on the first attempt!



Keio University School of Medicine



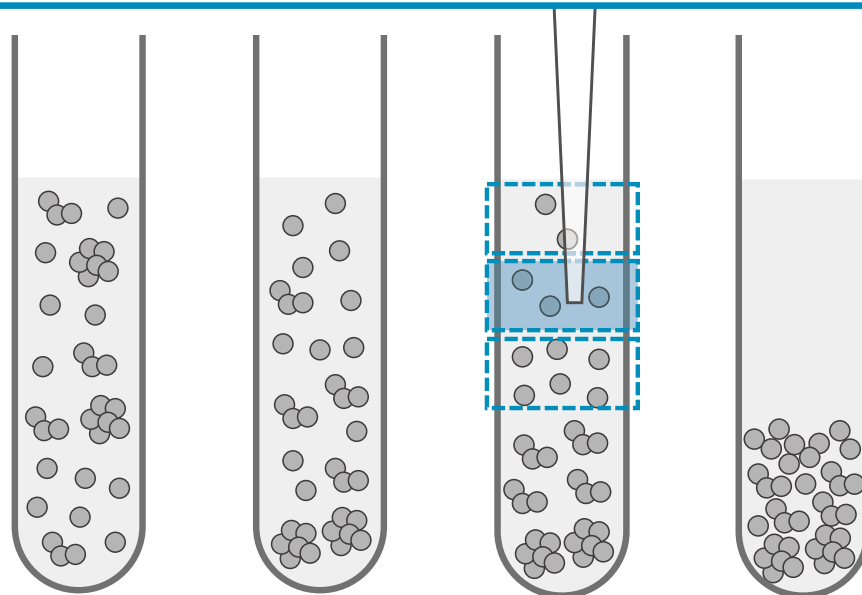
# Why do LabDroids succeed?

Reasons for difficulty: Two conflicting factors

Cells must be separated into single cells and then inoculated in each well evenly

Pipetting into single cell completely damaged cells

Retrieve only from particular depth where cells are dispersed equally with optimum density



0 sec

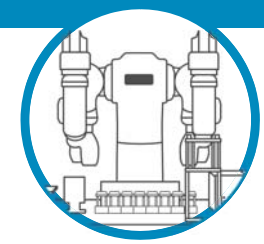
3 sec

6 sec

9 sec

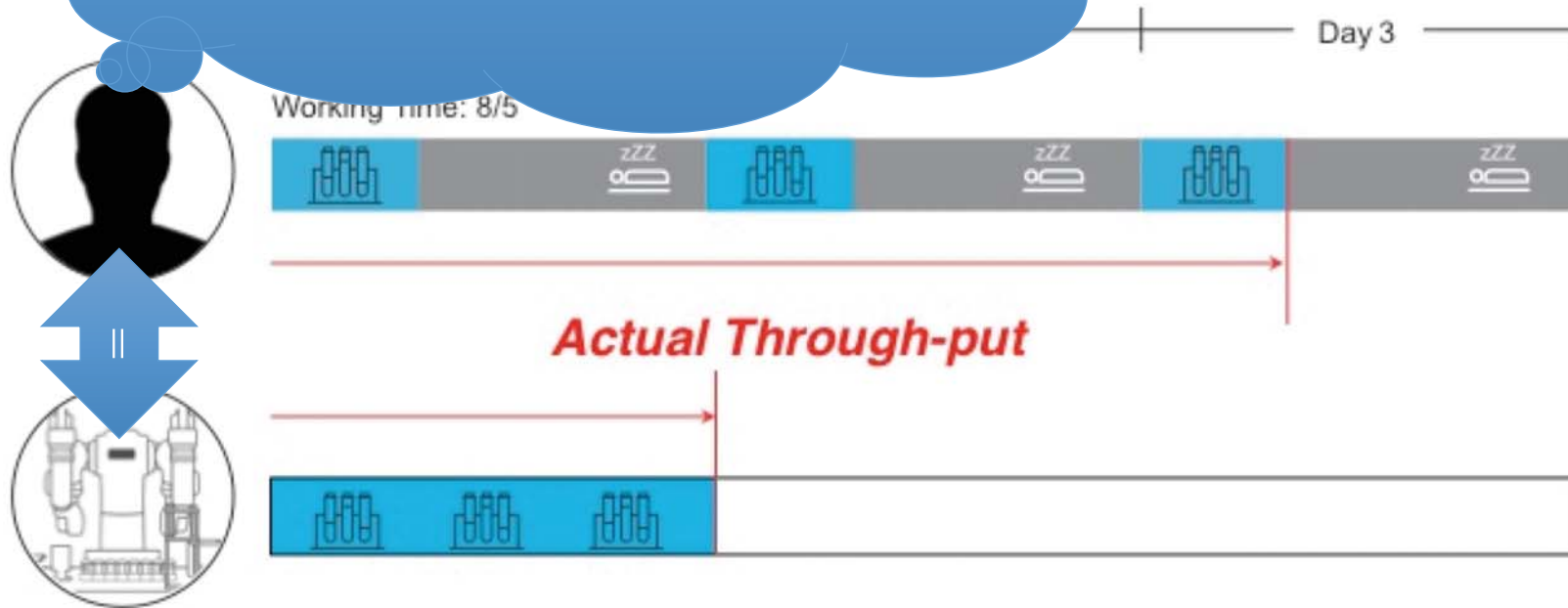
Items optimized

- 1) Dispersion Intensity (viability > 90%)
- 2) Depression time
- 3) Tip position



LabDroid-Researcher  
collaboration found condition in  
just one week!

ChIP protocol = 17hrs  
Humans can not complete the workflows  
in a normal 8-hour work day



# Automation of life science

past, present, and future

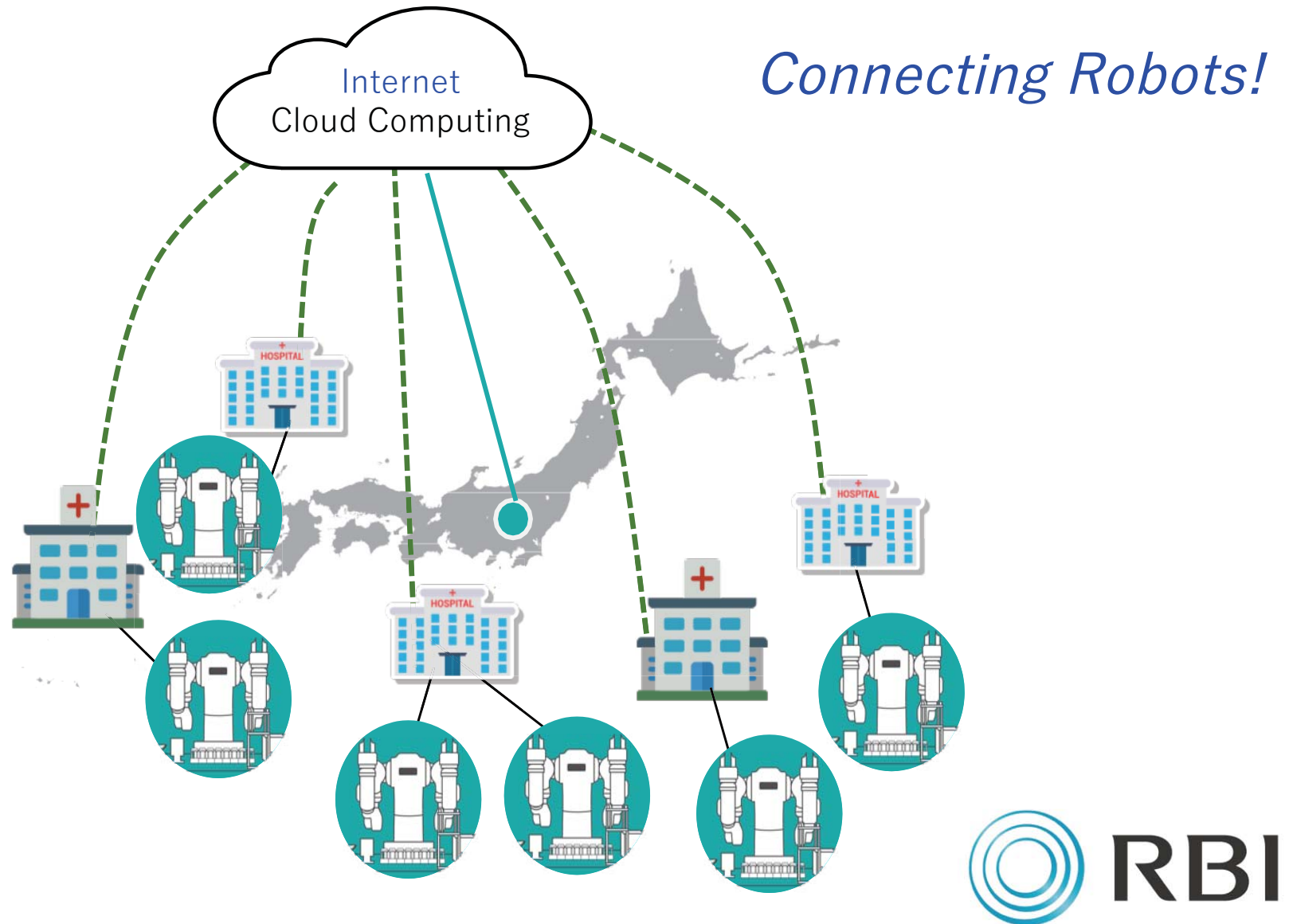


# Automation of life science

past, present, and future

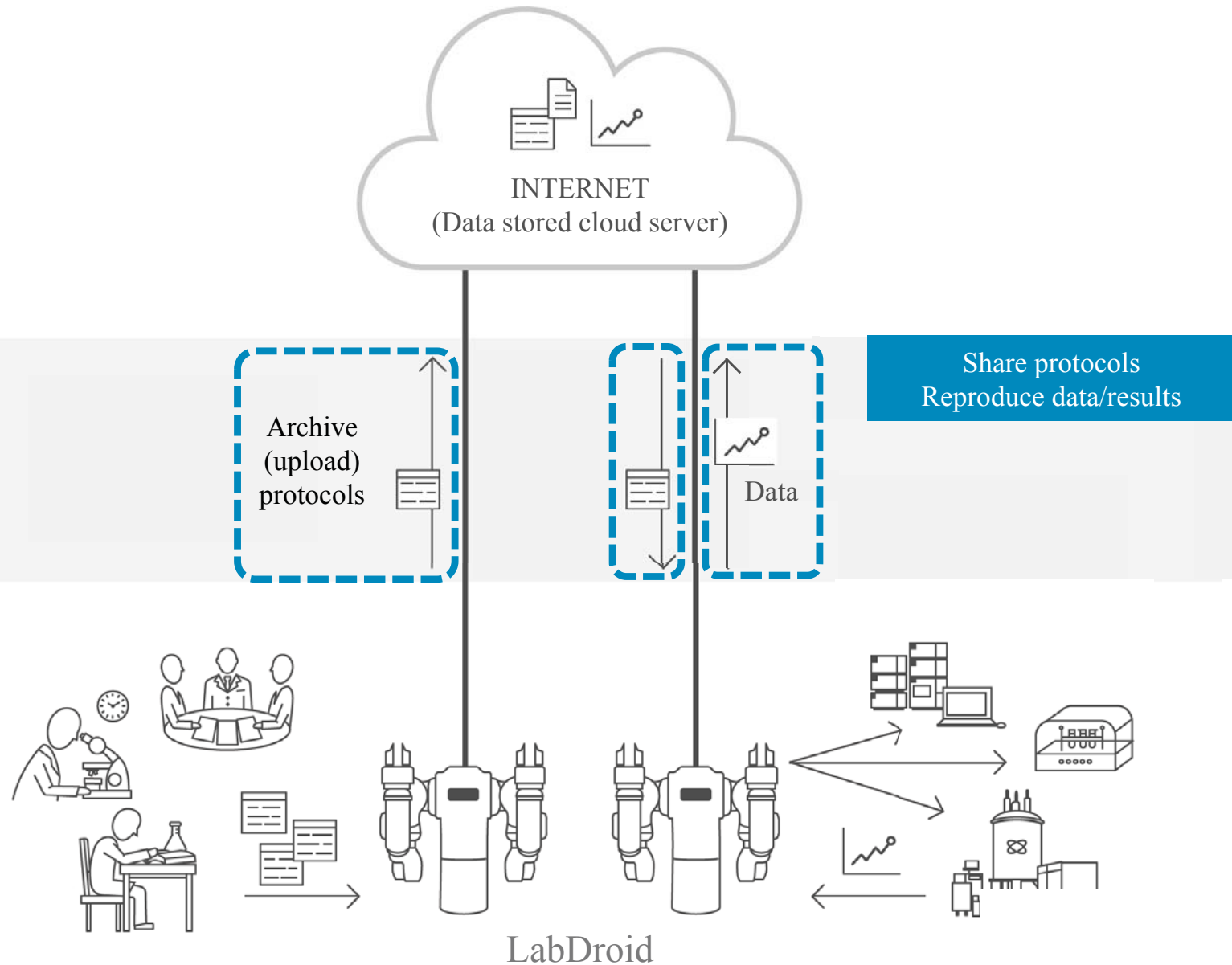


# 16 LabDroids are already hard at work in JAPAN

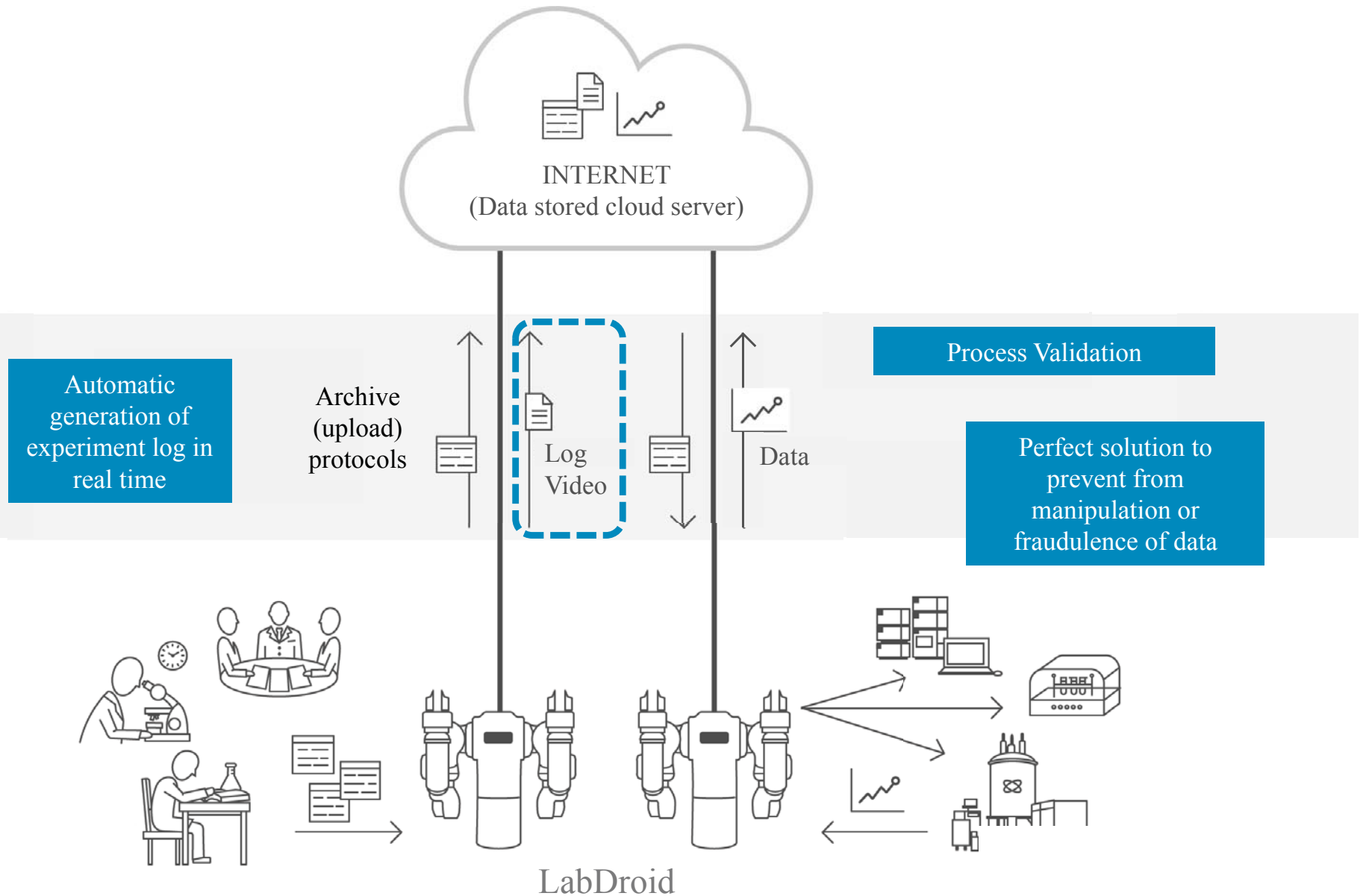




# Total laboratory management system



# Total Laboratory Management System

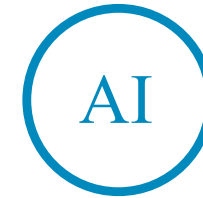


# LabSphere : Laboratory on Cloud

Language for protocols



BigData



Automatic generation of experiment log in real time

Archive (upload) protocols



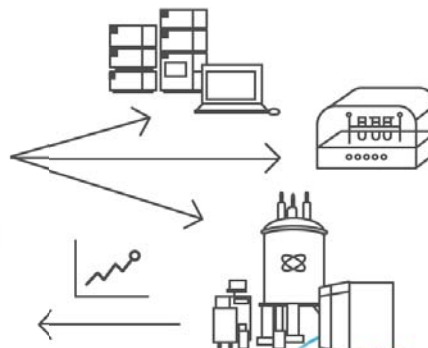
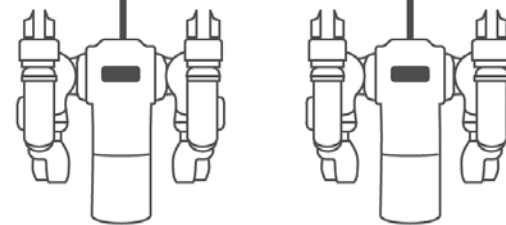
Log Video



Data

Re-use protocols  
Reproduce data/results

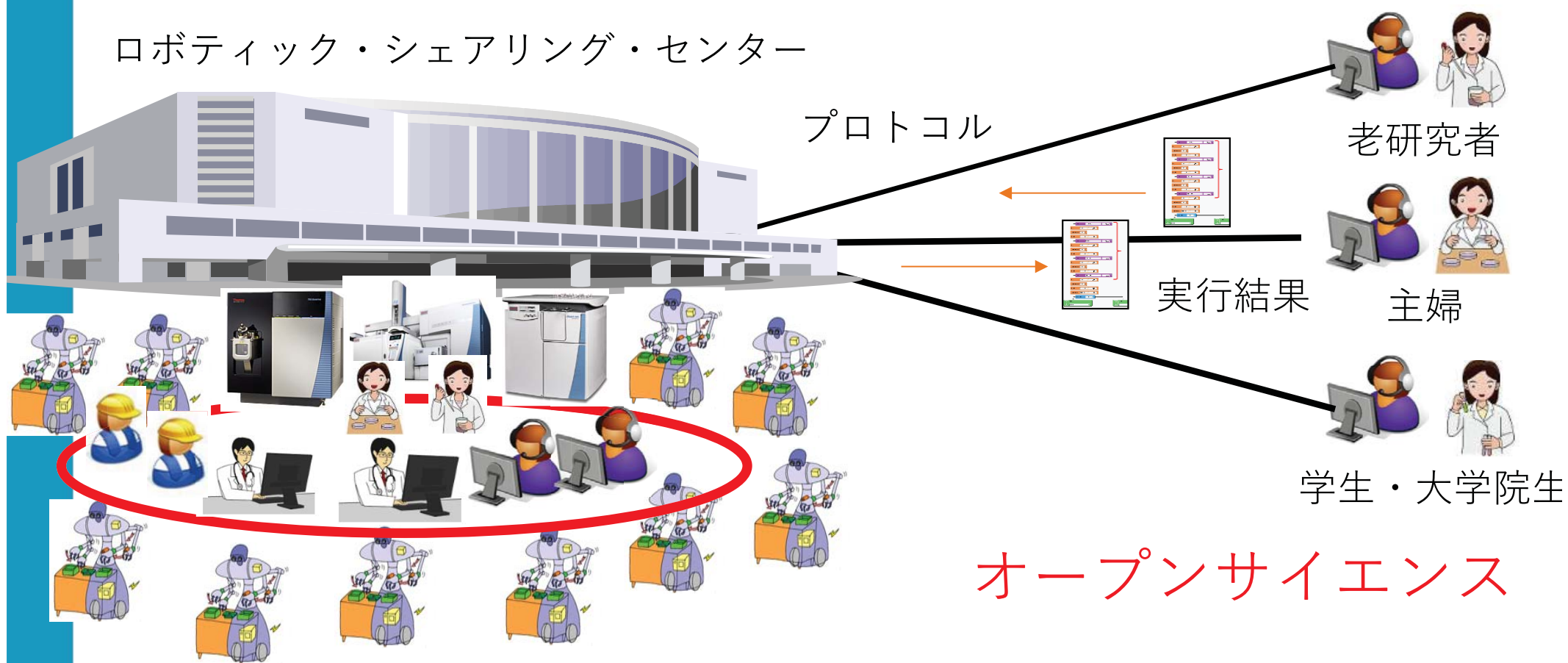
Perfect solution prevents manipulation or fraudulence of data



LabDroid



# 働き方の未来：在宅研究の促進



徹底的な人材活用  RBI

# 次の未来：クラウドで繋がっていく ～大規模ロボット研究拠点の創成

ローカル・ラボ



グローバル展開

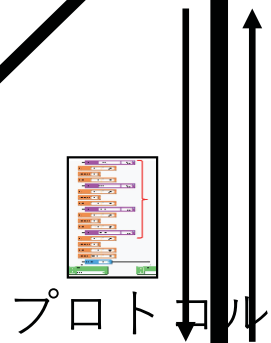
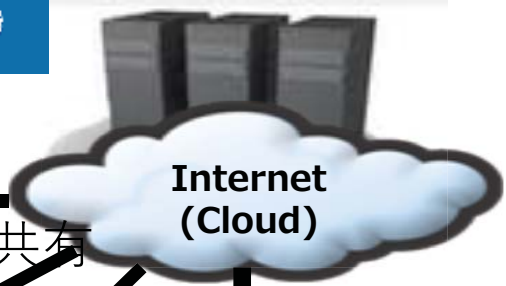
ローカル・ラボ

ユーザー

大学研究室

製薬企業

プロトコル共有



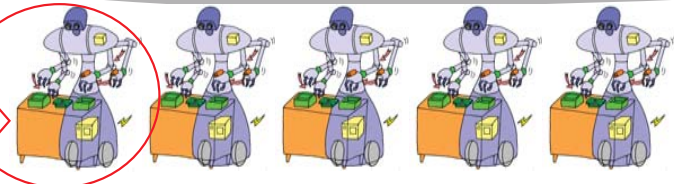
メリット

- ・大型解析機器の稼働率アップ
- ・水平型分業・研究拠点の差別化

プロトコル



同じプロトコルなら  
同じ結果がでる

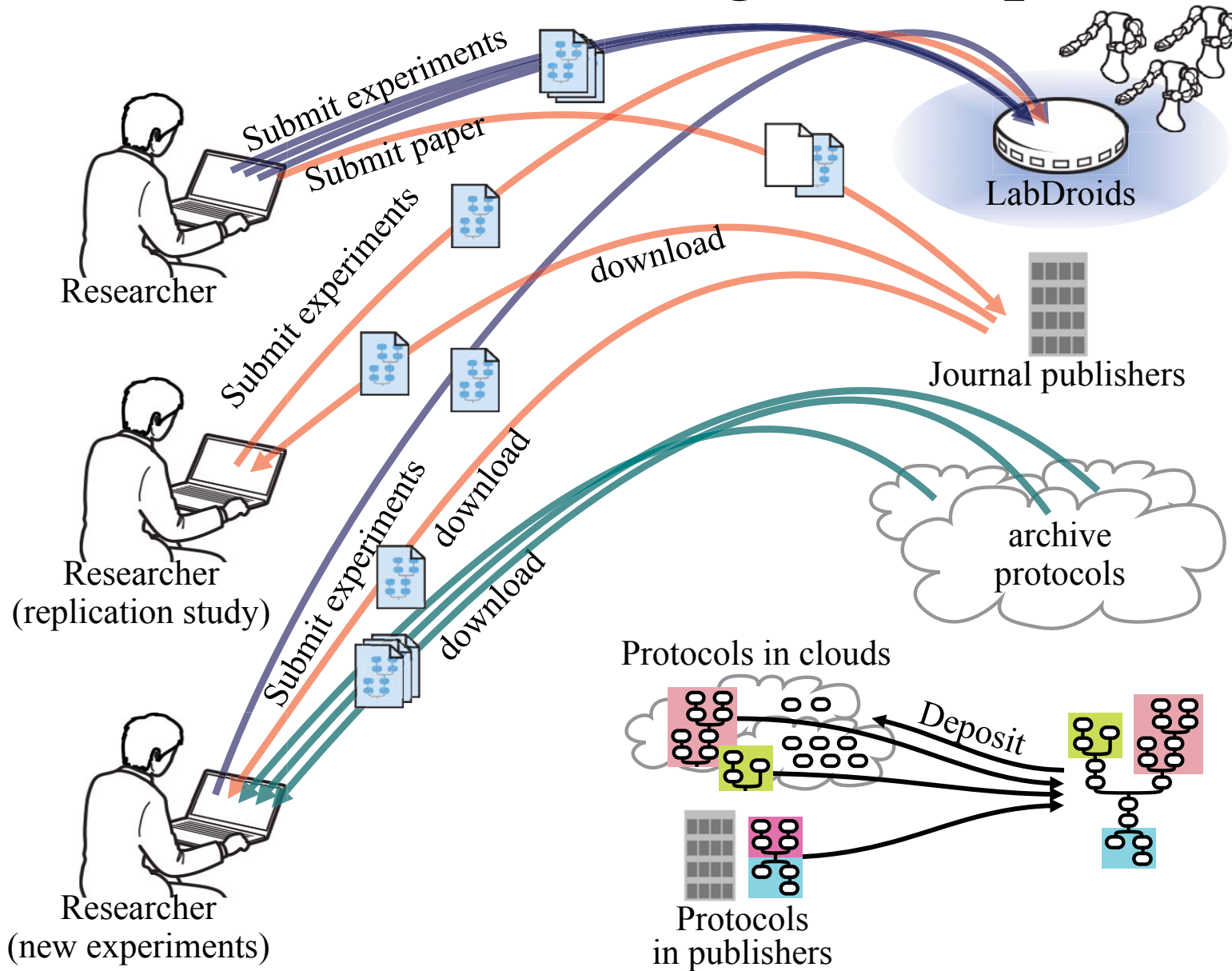


第三者認証が可能

大規模ロボット研究拠点（解析機器の一局集中化）



# Collaboration through LabSphere



N Yachie, T Natsume. "Robotic crowd biology with Maholo LabDroids", *Nature Biotech.* 35, 310–312 (2017).



# ■ ライフサイエンス/バイオインダストリーの抱える問題

## 研究生産性の低さと再現性

研究・実験が再現しない理由  
技術と経験が、暗黙知として  
個人に囲い込まれているため、  
再利用・共有が不可能。  
実験の成功は個人の技術・経験  
頼り、その上再現性が低い。

担当者が変わると、プロジェクトが頓挫する。前任者の技術基盤が、何も残らない。人材確保が困難。研究開発の安定的継続の危機！

過去5年間 = 8.6兆円  
今後2～3倍増加予測

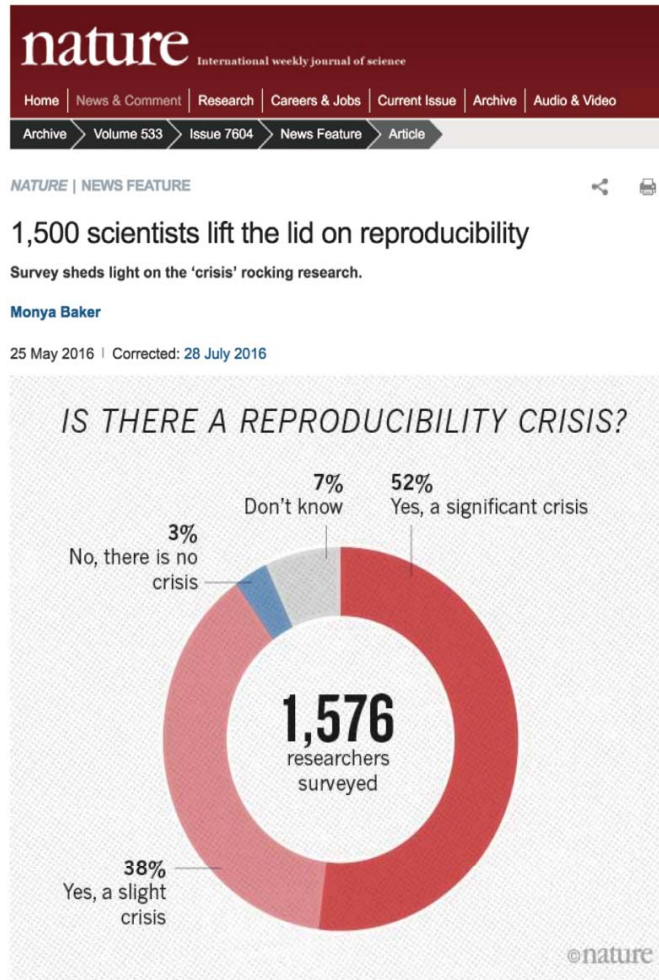
新薬開発は産業として成り立たなくなる・・・

結果：無駄な失敗、  
堂々巡り、試行錯誤を  
延々と繰り返す！  
=膨大なコストと時間  
研究生産性が低い真因

スキル・経験の必要  
な最先端技術の  
導入が困難

# 「再現性の危機」は問題点の根幹

Nature誌を初め、ライフサイエンス界では、「根源的な問題」として認識



(Baker M., Nature, 533, 2016)

## 現在の生命科学の問題点

- 再現性
  - M Baker, Nature (2016)
    - 52%の人が「深刻な問題がある」と答えている
    - 70%の人が「実験の再現に失敗したことがある」
  - Iqbal SA et.al., Plos Biol. (2016)
    - 267/268の論文の手法の記述が不十分
- 不正行為
- 労働集約的なワークスタイル

## 再現性は他の問題点の根幹である

- 再現性
  - あるところで行った実験が、別のところでも再現するから、巨人の肩の上に立てる
- 不正行為
  - 簡単に（他人の）実験が再現できないから、不正行為をしてしまう
- 労働集約的なワークスタイル
  - 同じ作業を正確に何度も繰り返すことは、人間には難しい



# MAHOLLO

# まほろ

 **RBI** Robotic Biology Institute Inc.

 **YASKAWA**

 独立行政法人  
**科学技術振興機構**  
Japan Science and Technology Agency

 **産総研**  
国立研究開発法人 産学技術総合研究所  
NATIONAL INSTITUTE OF  
ADVANCED INDUSTRIAL SCIENCE AND TECHNOLOGY (AIST)

内閣府産学官連携功労賞／ロボット大賞受賞